

① ML-II hyperparameter estimation:

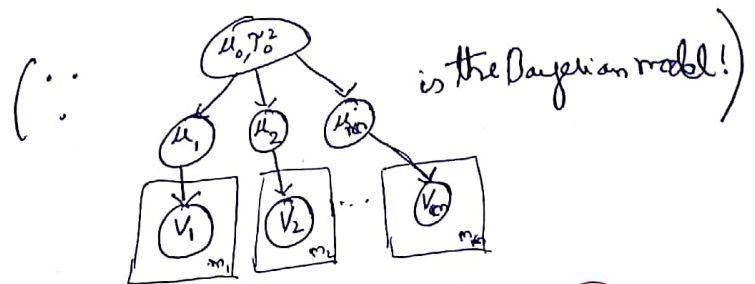
$$(\hat{\mu}_0, \hat{\tau}_0^2) \equiv \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} p(D/\mu_0, \tau_0^2)$$

~~$\underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \int \dots \int p(D/\mu_1, \dots, \mu_m) p(\mu_1, \dots, \mu_m/\mu_0, \tau_0^2) d\mu_1 \dots d\mu_m$~~ ~~(Total prob. rule, assume m's no faculty)~~

$$= \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \int \dots \int p(D/\mu_1, \dots, \mu_m) p(\mu_1, \dots, \mu_m/\mu_0, \tau_0^2) d\mu_1 \dots d\mu_m$$

(\therefore Total prob. rule, assume m's no faculty)

$$= \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \int \dots \int p(D_1/\mu_1) \dots p(D_m/\mu_m) p(\mu_1/\mu_0, \tau_0^2) \dots p(\mu_m/\mu_0, \tau_0^2) d\mu_1 \dots d\mu_m$$



$$= \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \prod_{i=1}^m \left[\int p(D_i/\mu_i) p(\mu_i/\mu_0, \tau_0^2) d\mu_i \right]$$

~~(Total prob. rule, assume m's no faculty)~~

$$= \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \prod_{i=1}^m \left[\int \prod_{j=1}^{m_i} p(v_{ij}/\mu_i) p(\mu_i/\mu_0, \tau_0^2) d\mu_i \right] \rightarrow \text{4.5 marks}$$

$$= \underset{\mu_0, \tau_0^2}{\operatorname{argmax}} \prod_{i=1}^m \left[\int \frac{e^{-\frac{1}{2} \frac{\sum_{j=1}^{m_i} (v_{ij} - \mu_i)^2}{\sigma^2}} - \frac{(\mu_i - \mu_0)^2}{2\tau_0^2}}{\tau_0} d\mu_i \right]$$

$$= \underset{\mu_0, \tau_0^2}{\text{argmax}} \prod_{i=1}^m \frac{e^{-\frac{(\sum_{j=1}^{m_i} v_{ij} - \mu_0)^2}{2(\tau_0^2 + \sigma^2)}}}{\sqrt{2\pi(\tau_0^2 + \sigma^2)}}$$

(by completing squares. 11th exercises done before. See (5-90) in book)

$$= \underset{\mu_0, \tau_0^2}{\text{argmax}} \frac{e^{-\sum_{i=1}^m \frac{(\sum_{j=1}^{m_i} v_{ij} - \mu_0)^2}{2(\tau_0^2 + \sigma^2)}}}{\left(\sqrt{2\pi(\tau_0^2 + \sigma^2)}\right)^m}$$

↓
Similar to MLE with Gaussian model & data $\frac{\sum_{j=1}^{m_1} v_{1j}}{m_1}, \dots, \frac{\sum_{j=1}^{m_m} v_{mj}}{m_i}$.

$$\Rightarrow \hat{\mu}_0 = \frac{\sum_{i=1}^m \left(\sum_{j=1}^{m_i} v_{ij} / m_i \right)}{m}, \quad \hat{\tau}_0^2 \neq \sigma^2 = \frac{\sum_{i=1}^m \left(\left(\sum_{j=1}^{m_i} v_{ij} / m_i \right) - \hat{\mu}_0 \right)^2}{m}$$

(sample mean) (sample variance)

→ 2.5 marks.

~~$$p(\mu_1, \dots, \mu_m | \mathcal{D}) \propto p(\mathcal{D} | \mu_1, \dots, \mu_m)$$~~

$$p(\mu_1, \dots, \mu_m | \mathcal{D}, \hat{\mu}_0, \hat{\tau}_0^2) \propto \prod_{i=1}^m \prod_{j=1}^{m_i} p(v_{ij} | \mu_i) p(\mu_i | \hat{\mu}_0, \hat{\tau}_0^2) \quad (\because \text{Same Bayes's rule as earlier})$$

$$\propto \prod_{i=1}^m e^{-\frac{1}{2} \left[\sum_{j=1}^{m_i} \frac{(v_{ij} - \mu_i)^2}{\sigma^2} + \frac{(\mu_i - \hat{\mu}_0)^2}{\hat{\tau}_0^2} \right]}$$

$$\propto \prod_{i=1}^m e^{-\frac{1}{2} \left(\mu_i - \frac{\frac{m_i \bar{v}_i}{\sigma^2} + \frac{\hat{\mu}_0}{\hat{\tau}_0^2}}{\left(\frac{1}{\sigma^2} + \frac{1}{\hat{\tau}_0^2} \right)} \right)^2}$$

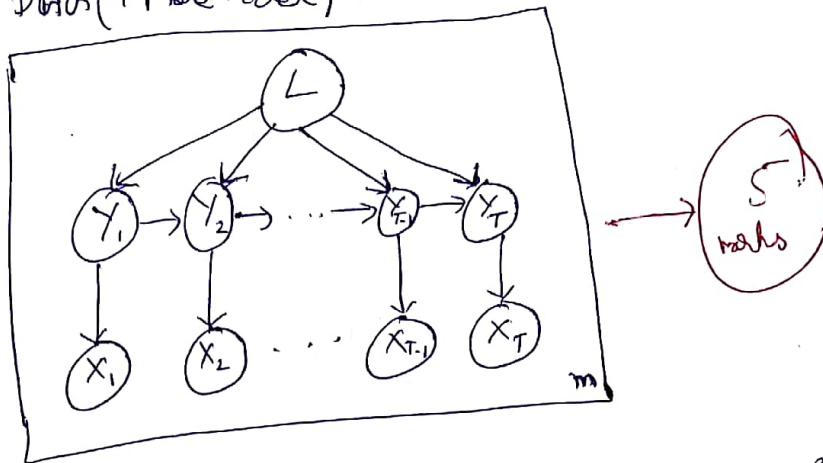
$\frac{1}{\sigma^2} + \frac{1}{\hat{\tau}_0^2}$

(\because completing squares in μ_i)

$$\Rightarrow \hat{\mu}_{10}^{\text{MAP}} = \frac{\frac{m \bar{v}_i}{\sigma^2} + \frac{\hat{\mu}_0}{\hat{\tau}_0^2}}{\frac{1}{\sigma^2} + \frac{1}{\hat{\tau}_0^2}}$$

→ 5 marks.

2) Here is the DAG (+ plate model):



L modeled by Multinoulli \rightarrow parameters: $(\theta_1, \theta_2, \theta_3) \geq 0, \sum_{i=1}^3 \theta_i = 1$.

$Y_i / L = l$ is modeled by Multinoulli \rightarrow parameters $(\pi_{l1}, \dots, \pi_{lc}) \geq 0, \sum_{i=1}^c \pi_{li} = 1$

$Y_t / Y_{t-1}, L = l$ is modeled by Transition prob. matrix is parameter A_1, A_2, A_3 , each is a stochastic matrix.
by Multinoullis

$X_t / Y_t = s, L = l$ is modeled using exponential family model with parameters, ~~$w_{t,s}$~~

e.g. $w_{11}, \dots, w_{1c} \rightarrow \text{language 1}$
 $w_{21}, \dots, w_{2c} \rightarrow \text{" 2}$
 $w_{31}, \dots, w_{3c} \rightarrow \text{" 3}$
 $\downarrow \quad \quad \quad \downarrow$
 $\text{state 1} \quad \dots \quad \text{state c}$

$\rightarrow 2 \text{ nobs}$

$$p(x) = \sum_{y \neq l} p(x, y, l)$$

$$= \sum_{y \neq l} p(x_1 / y_1) \dots p(x_T / y_T) p(y_1 / l) p(y_2 / y_1, l) \dots p(y_T / y_{T-1}, l) p(l)$$

(\because chainrule for above BN)

~~SA state~~

$$\log(p(\mathcal{D})) = \sum_{i=1}^m \log p(x_i)$$

$$= \sum_{i=1}^m \log \left(\sum_{l=1}^3 p(x_i/l) p(l) \right)$$

This is same as that for Mixture model.

$$\therefore q_i(l)^{(k)} \equiv p^{(k-1)}(l/x_i)$$

$$\hat{\Theta}_l^{(k)} = \frac{\sum_{i=1}^m q_i^{(k)}(l)}{\sum_{l=1}^3 \sum_{i=1}^m q_i^{(k)}(l)}$$

Same as in mixture model.

But, computationally $p(l/x_i)$ may be a challenge!

2 marks

The other terms are:

$$\text{argmax}_{\pi_l, A_l, w_{l1}, \dots, w_{lc}} \sum_{i=1}^m q_i(l) \log p(x_i/l)$$

$\forall l=1,2,3.$

$$= \text{argmax}_{\pi_l, A_l, w_{l1}, \dots, w_{lc}} \sum_{i=1}^m q_i(l) \log \left(\sum_{y \neq y_i} p(x_{i1}/y_i) \dots p(x_{iT}/y_i) p(y/l) p(y/x_i, l) \right)$$

(This is like weighted samples ~~in~~ EM with HMM!)

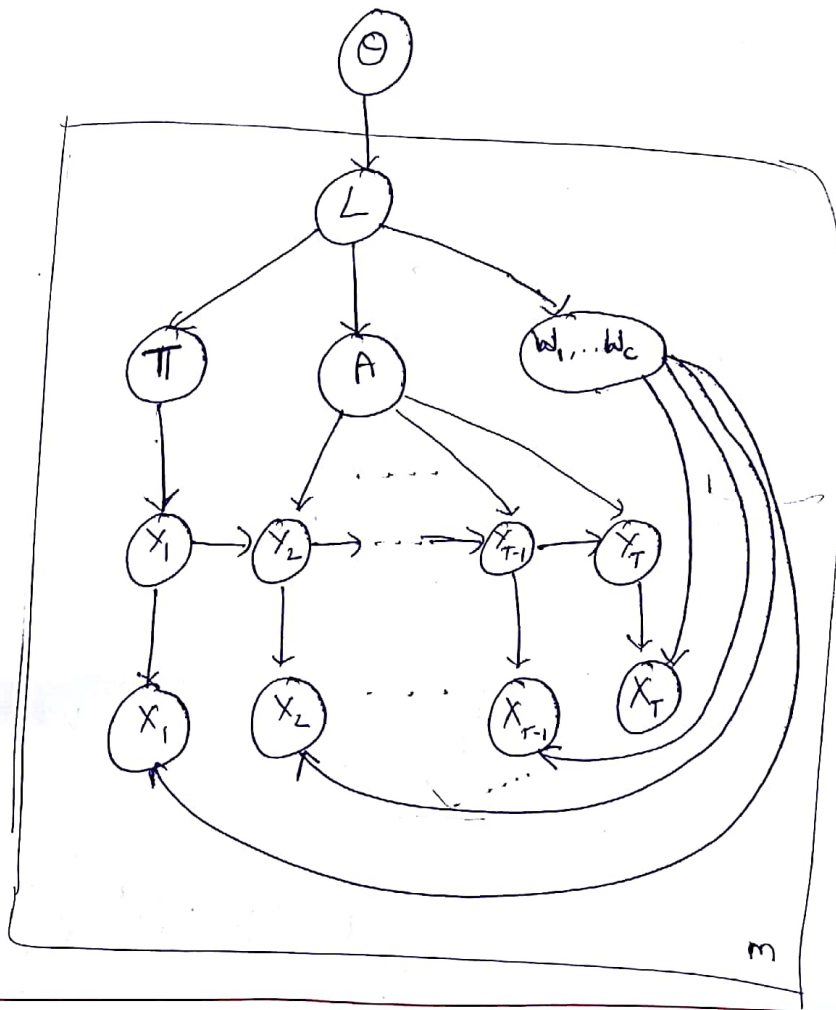
$$\therefore \hat{\pi}_{l0}^{(k)} = \frac{\sum_{i=1}^m q_i^{(k)}(l) p(y_{i1}=0/x_i, l)}{\sum_{d'=1}^c \sum_{i=1}^m q_i^{(k)}(l) p(y_{i1}=d'/x_i, l)} \rightarrow \text{2 marks}$$

$$\hat{A}_{ljk}^{(k)} = \frac{\sum_{i=1}^m \sum_{t=2}^{T_i} q_i^{(k)}(l) p(y_{i,t+1}=j, y_{i,t}=k/x_i, l)}{\sum_{j'=1}^J \sum_{k'=1}^K \sum_{i=1}^m \sum_{t=2}^{T_i} q_i^{(k)}(l) p(y_{i,t+1}=j', y_{i,t}=k'/x_i, l)} \rightarrow \text{2 marks}$$

$$E_{\hat{w}_{lj}} [\phi(x_j)] = \frac{\sum_{i=1}^m \sum_{t=1}^{T_i} q_i^{(k)}(l) p(y_{i,t}=j/x_i) \phi(x_{i,t})}{\sum_{i=1}^m \sum_{t=1}^{T_i} q_i^{(k)}(l) p(y_{i,t}=j/x_i)} \rightarrow \text{2 marks}$$

4

Here is a DAG for the Bayesian model:



5 marks

③ $I_g(g)$: we need CI of the form: $A, \boxed{?} \perp \boxed{?} / J$

Since any path from A to others is d-separated by J, because of 'v' structure, there is no CI that is true.

\therefore From $I_g(g)$ we have empty set!

2 marks

$I_o(g) \rightarrow \cancel{D \perp A} / A \perp B$

$C \perp (A, B)$

$D \perp (A, C) / B$

1.5 marks

~~$I_o(g) \rightarrow A \perp (B, C, D, E, F)$~~
 ~~$B \perp (A, C, D, E, F)$~~
 ~~$C \perp (A, B, D, E, F)$~~

~~1.5 marks~~

5

$$I_2(g) \rightarrow E \perp (A, C, D, F, G, J) / B$$

$$F \perp (A, B, D, E, G, H, J) / C$$

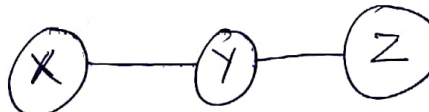
→ 1.5 marks

$$G \perp (B, C, E, F, H, I) / (A, D)$$

④ Idea is to write p in canonical form and look at the factors. ~~Factor with not exist~~

For Gaussian a pairwise-rcpe will not exist iff corresponding covariance inverse term is zero!

It is easy to verify that only cofactor of 1, 3 position is zero \therefore the only rcpe about must be X, Z

$\Rightarrow H =$  is the perfect I MAP

$$I_g(H) = \{ X \perp Z / Y \} \rightarrow 1.5 \text{ marks}$$

⑤ Least no. factors are possible iff only maximal cliques are selected.

$\therefore \{C, D\} \quad \{S, L, J\}$

$\{D, I, G\} \quad \{S, I\}$

$\{G, J, H\}$

$\{G, L, J\}$

only 6 factors!

5 marks