

Nonhomogeneous Linear Systems: Method of Undetermined Coefficients

$$\vec{X}' = A\vec{X} + \vec{g} \quad : \text{To find particular solution!}$$

General tricks:

- If \vec{g} involves exponential ~~terms~~ terms, try a particular solution of the form $\vec{X}_p = \vec{v}[\text{exponential term}]$.

- If the exponential term is part of the homogeneous solution, the try $\vec{X}_p = t \vec{v}[\text{exponential term}] + \vec{w}[\text{exponential term}]$

- If \vec{g} has a cos or sine term, solve the more general problem with the nonhomogeneous term replaced with $e^{i\omega t}$. Recall that $\cos \omega t = \text{Re}[e^{i\omega t}]$
 $\sin \omega t = \text{Im}[e^{i\omega t}]$.

- If \vec{g} is constant, then let $\vec{X}_p = \vec{v}$ also a constant vector.

The goal in each case is to find \vec{v} .

Let us see a few examples to clarify the above points.

Ex 1. Constant \vec{g} case!

$$\vec{X}' = \begin{bmatrix} -2 & 2 \\ 1 & -2 \end{bmatrix} \vec{X} + \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A = \begin{bmatrix} -2 & 2 \\ 1 & -2 \end{bmatrix}$$

find the particular solution.

$$\vec{g} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Solution: Since $\vec{g} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is a constant vector, we try

$$\vec{X}_p = \vec{v} \rightarrow \text{constant vector.}$$

$$\therefore \vec{X}_p' = 0$$

Substituting \vec{X}_p in $\vec{X}' = A\vec{X} + \vec{g}$, we get

$$0 = A\vec{v} + \vec{g} \Rightarrow A\vec{v} = -\vec{g}$$

$$\Rightarrow \begin{bmatrix} -2 & 2 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = -\begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \vec{v} = -\begin{bmatrix} -2 & 2 \\ 1 & -2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = -\frac{\begin{bmatrix} -2 & -2 \\ -1 & -2 \end{bmatrix}}{4-2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= -\frac{1}{2} \begin{bmatrix} -2 & -2 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -4 \\ -3 \end{bmatrix} = \begin{bmatrix} 2 \\ 3/2 \end{bmatrix}$$

$$\therefore \vec{X}_p = \begin{bmatrix} 2 \\ 3/2 \end{bmatrix}$$

Homogeneous Solution: $\vec{X}' = \begin{bmatrix} -2 & 2 \\ 1 & -2 \end{bmatrix} \vec{X}$

Eigenvalues: $[A - \lambda I] = 0 \Rightarrow (-2-\lambda)(-2-\lambda) - 2 = 0$

$$\Rightarrow x^2 + 4x + 2 = 0$$

$$\Rightarrow x_1 = -2 - \sqrt{2}$$

$$x_2 = \sqrt{2} - 2$$

Eigenvalues:

with $x_1 = -2 - \sqrt{2}$, $\vec{\xi}^{(1)} = \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix}$

with $x_2 = \sqrt{2} - 2$; $\vec{\xi} = \begin{bmatrix} \sqrt{2} \\ 1 \end{bmatrix}$

\therefore Homogeneous solution: $\vec{X}_H = c_1 \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix} e^{(-2-\sqrt{2})t} + c_2 \begin{bmatrix} \sqrt{2} \\ 1 \end{bmatrix} e^{(\sqrt{2}-2)t}$

General solution, $\vec{X} = \vec{X}_H + \vec{X}_P$

Ex: Constant \vec{g} case: second type of solution:

$$\vec{X}' = \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} \vec{X} + \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

- Check determinant first: Here $|A| = 2 - 2 = 0$
- \therefore If $\vec{X}_P = \vec{v}$, then we get $A\vec{v} + \vec{g} = 0$
- $\Rightarrow \vec{v} = -A^{-1}\vec{g}$

Since $|A| = 0$, we cannot calculate A^{-1} .

• Try $\vec{X}_P = \vec{v}t + \vec{w}$

Then $\vec{X}'_P = \vec{v}$

Substitute \vec{X}_P in $\vec{X}' = A\vec{X} + \vec{g}$, we get

$$\vec{v} = A[\vec{v}t + \vec{\eta}] + \vec{g}$$

$$\Rightarrow \vec{v} = tA\vec{v} + A\vec{\eta} + \vec{g}$$

Equating similar coefficients on both sides:

$$0(t): \quad A\vec{v} = 0 \quad \text{--- ①}$$

$$\text{Other terms: } \quad A\vec{\eta} = \vec{v} - \vec{g} \quad \text{--- ②}$$

$$\text{From ①, } \quad A\vec{v} = 0 \quad \Rightarrow \quad \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} \vec{v} = 0$$

$$\Rightarrow \left. \begin{array}{l} -2v_1 + 2v_2 = 0 \\ v_1 - v_2 = 0 \end{array} \right\} v_1 = v_2$$

If $v_1 = M$ (some scalar), then $v_2 = M$

$$\therefore \vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = M \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Now, from ②: } \quad A\vec{\eta} = \vec{v} - \vec{g}$$

$$\Rightarrow \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = M \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} M-1 \\ M-2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \begin{bmatrix} M-1 \\ M-2 \end{bmatrix}$$

Row operation: Set Row 2 = $\frac{1}{2}$ Row 1 + Row 2

$$\Rightarrow \begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \begin{bmatrix} M-1 \\ \frac{1}{2}(M-1) + (M-2) \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \begin{bmatrix} M-1 \\ \frac{3M}{2} - \frac{5}{2} \end{bmatrix}$$

We must set $\frac{3M}{2} - \frac{5}{2} = 0 \rightarrow M = \frac{5}{3}$ for a solution.

$$\text{Then } -2\eta_1 + 2\eta_2 = \frac{5}{3} - 1 = \frac{2}{3}$$

$$\Rightarrow -\eta_1 + \eta_2 = \frac{1}{3}$$

Let $\eta_2 = K$, then $\eta_1 = \eta_2 - \frac{1}{3} = K - \frac{1}{3}$
↓
arbitrary constant

$$\therefore \vec{\eta} = \begin{bmatrix} K - \frac{1}{3} \\ K \end{bmatrix} = K \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

Without loss of generality, we can choose $K=0$.

$$\therefore \vec{\eta} = \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

$$\therefore \vec{X}_p = \vec{v}t + \vec{\eta} = M \begin{bmatrix} 1 \\ 1 \end{bmatrix} t + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

$$\vec{X}_p = \frac{5}{3} \begin{bmatrix} 1 \\ 1 \end{bmatrix} t + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

Ex 1: \vec{g} involving exponential terms.

$$\vec{x}' = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \vec{x} + e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad (*)$$

• Homogeneous Solution:- $\vec{x}' = A \vec{x}$, $A = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$

$$\text{Put } \vec{x} = \vec{\xi} e^{\lambda t} \Rightarrow \vec{\xi} \lambda e^{\lambda t} = A \vec{\xi} e^{\lambda t}$$

$$\Rightarrow (A - \lambda I) \vec{\xi} = 0$$

$$\text{Eigenvalues: } |A - \lambda I| = 0 \rightarrow (-2-\lambda)(-2-\lambda) - 1 = 0$$

$$\rightarrow (\lambda + 2)^2 = 1$$

$$\rightarrow \lambda + 2 = \pm 1$$

$$\rightarrow \lambda_1 = -1, \lambda_2 = -3$$

$$\text{Eigenvectors: (i) } (A - \lambda_1 I) \vec{\xi}^{(1)} = 0 \rightarrow \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} = 0 \Rightarrow \vec{\xi}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$(ii) (A - \lambda_2 I) \vec{\xi}^{(2)} = 0 \rightarrow \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} = 0 \Rightarrow \vec{\xi}^{(2)} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{Homogeneous Solution: } \vec{x}_H = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-3t}$$

• Particular Solution:- Since \vec{g} has a e^{2t} term in (*), we have to try $\vec{x}_P = \vec{v} e^{2t}$.

$$\Rightarrow \vec{x}' = 2\vec{v} e^{2t}$$

$$\Rightarrow 2\vec{v}e^{2t} = A\vec{v}e^{2t} + \vec{g}$$

$$\Rightarrow 2\vec{v}e^{2t} = A\vec{v}e^{2t} + e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Canceling the e^{2t} terms, we have

$$2\vec{v} = A\vec{v} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow A\vec{v} - 2\vec{v} = -\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow (A - 2I)\vec{v} = -\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -4 & 1 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = -\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = -\frac{\begin{bmatrix} -4 & -1 \\ -1 & -4 \end{bmatrix}}{15} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{15} \begin{bmatrix} -4 \\ -1 \end{bmatrix} = \begin{bmatrix} 4/15 \\ 1/15 \end{bmatrix}$$

$$\Rightarrow \vec{v} = \begin{bmatrix} 4/15 \\ 1/15 \end{bmatrix}$$

\therefore Particular solution, $\vec{x}_p = \begin{bmatrix} 4/15 \\ 1/15 \end{bmatrix} e^{2t}$

$$\therefore \vec{x} = \vec{x}_h + \vec{x}_p$$

$$= c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-3t} + \begin{bmatrix} 4/15 \\ 1/15 \end{bmatrix} e^{2t}$$

Ex: \vec{g} with exponential terms, ~~where~~ e^{dt} , where d is one of the eigenvalues.

$$\vec{x} = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \vec{x} + e^{-t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Now $\vec{g} = e^{-t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

The homogeneous problem is the same as in the previous example.

$$\Rightarrow \lambda_1 = -1 \quad \& \quad \lambda_2 = -3.$$

• Now if we try $\vec{x}_p = \vec{v} e^{-t}$, then

$$-\vec{v} e^{-t} = A \vec{v} e^{-t} + e^{-t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow (A+I) \vec{v} = - \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

We cannot solve for \vec{v} since $|A+I| = 0$

• Therefore, we try $\vec{x}_p = \vec{v} t e^{-t} + \vec{\eta} e^{-t}$

$$\text{Thus } \vec{x}_p' = \vec{v} e^{-t} - \vec{v} t e^{-t} + \vec{\eta} (-e^{-t})$$

$$\rightarrow \vec{v} e^{-t} - \vec{v} t e^{-t} - \vec{\eta} e^{-t} = A [\vec{v} t e^{-t} + \vec{\eta} e^{-t}] + e^{-t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Cancelling e^{-t} terms, we get

$$\rightarrow \vec{v} - \vec{v} t - \vec{\eta} = t A \vec{v} + A \vec{\eta} + \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Equating terms of similar type on both sides:

$$0(t) \text{ terms: } A \vec{v} = -\vec{v} \rightarrow (A+I) \vec{v} = 0$$

$$\text{other terms: } \vec{v} - \vec{\eta} = A \vec{\eta} + \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\bullet \quad (A+I)\vec{v} = 0 \quad \rightarrow \quad \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \quad \left. \begin{array}{l} -v_1 + v_2 = 0 \\ v_1 - v_2 = 0 \end{array} \right\} v_1 = v_2$$

$$\therefore \text{If } v_1 = M, \text{ then } v_2 = M$$

$$\therefore \vec{v} = M \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \text{where } M \text{ is a scalar.}$$

$$\bullet \quad (A+I)\vec{\eta} = \vec{v} - \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= M \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} M-1 \\ M \end{bmatrix}$$

$$\text{Solve for } \vec{\eta}: \quad \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \begin{bmatrix} M-1 \\ M \end{bmatrix}$$

Row operation: Row 2 = Row 1 + Row 2

$$\rightarrow \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \begin{bmatrix} M-1 \\ 2M-1 \end{bmatrix}$$

We conclude that $2M-1=0$ is needed $\rightarrow M = \frac{1}{2}$

$$\text{Then } -\eta_1 + \eta_2 = M-1 = \frac{1}{2}-1 = -\frac{1}{2}$$

$$\Rightarrow -\eta_1 + \eta_2 = -\frac{1}{2}$$

$$\text{Let } \eta_2 = K \Rightarrow \eta_1 = K + \frac{1}{2}$$

$$\therefore \vec{\eta} = \begin{bmatrix} K + \frac{1}{2} \\ K \end{bmatrix} = K \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix}$$

Since k is arbitrary, we can set $k=0$

$$\therefore \vec{\eta} = \begin{bmatrix} 1/2 \\ 0 \end{bmatrix}$$

\therefore Particular solution is

$$\vec{X}_p = \vec{v} t e^{-t} + \vec{\eta} e^{-t}$$

$$= M \begin{bmatrix} 1 \\ 1 \end{bmatrix} t e^{-t} + \begin{bmatrix} 1/2 \\ 0 \end{bmatrix} e^{-t}$$

$$\vec{X}_p = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} t e^{-t} + \begin{bmatrix} 1/2 \\ 0 \end{bmatrix} e^{-t}$$

Ex: ~~Part~~ Nonhomogeneous term with trigonometric terms:

$$\vec{X}' = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \vec{X} + \cos t \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{--- (1)}$$

Solution: We can replace the $\cos t$ term with e^{it}
since $\cos t = \operatorname{Re}[e^{it}]$.

$$\text{Let } \vec{Y}' = A \vec{Y} + e^{it} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{--- (2)}$$

$$\text{Now } \vec{X}_p \text{ (our solution)} = \operatorname{Re}[\vec{Y}].$$

Let $\vec{Y} = \vec{v} e^{it}$. Substitute in (2), we get

$$\Rightarrow i \vec{v} e^{it} = A \vec{v} e^{it} + e^{it} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow i \vec{v} = A \vec{v} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow (A - i) \vec{v} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2-i & 1 \\ 1 & -2-i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -2-i & 1 \\ 1 & -2-i \end{bmatrix}^{-1} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \frac{\begin{bmatrix} -2-i & -1 \\ -1 & -2-i \end{bmatrix}}{(2+i)^2 - 1} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{2+4i} \begin{bmatrix} -(2+i) & -1 \\ -1 & -(2+i) \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{2+4i} \begin{bmatrix} 2+i \\ 1 \end{bmatrix}$$

Multiplying & dividing by $2-4i$, we get

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \frac{2-4i}{20} \begin{bmatrix} 2+i \\ 1 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} (1-2i)(2+i) \\ 1-2i \end{bmatrix}$$

$$= \frac{1}{10} \begin{bmatrix} 4-3i \\ 1-2i \end{bmatrix}$$

$$\vec{y} = \vec{v} e^{it} = \frac{1}{10} \begin{bmatrix} 4-3i \\ 1-2i \end{bmatrix} e^{it}$$

$$\therefore \vec{x}_p = \operatorname{Re}[\vec{y}] = \operatorname{Re}\left[\frac{1}{10} \begin{bmatrix} 4-3i \\ 1-2i \end{bmatrix} e^{it}\right]$$

$$= \frac{1}{10} \operatorname{Re} \left\{ \left(\begin{bmatrix} 4 \\ 1 \end{bmatrix} + i \begin{bmatrix} -3 \\ -2 \end{bmatrix} \right) (\cos t + i \sin t) \right\}$$

$$= \frac{1}{10} \left[\begin{bmatrix} 4 \\ 1 \end{bmatrix} \cos t - \begin{bmatrix} -3 \\ -2 \end{bmatrix} \sin t \right]$$

$$\vec{x}_p = \frac{1}{10} \begin{bmatrix} 4 \cos t + 3 \sin t \\ \cos t + 2 \sin t \end{bmatrix}$$