# Introduction to Machine-Independent Optimizations - 3 Data-Flow Analysis

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NPTEL Course on Principles of Compiler Design

- What is code optimization? (in part 1)
- Illustrations of code optimizations (in part 1)
- Examples of data-flow analysis
- Fundamentals of control-flow analysis
- Algorithms for two machine-independent optimizations
- SSA form and optimizations

- Sets of expressions constitute the domain of data-flow values
- Forward flow problem
- Confluence operator is ∩
- An expression x + y is available at a point p, if every path (not necessarily cycle-free) from the initial node to p evaluates x + y, and after the last such evaluation, prior to reaching p, there are no subsequent assignments to x or y
- A block kills x + y, if it assigns (or may assign) to x or y and does not subsequently recompute x + y.
- A block generates x + y, if it definitely evaluates x + y, and does not subsequently redefine x or y

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Set of all expressions = {f+1,a+7,b+d,d+c,a+4,e+c,a+b,c+f,e+a}

 $EGEN[B] = \{f+1,b+d,d+c\}$ EKILL[B] = {a+4,a+b,e+a,e+c,c+f,a+7}

The data-flow equations

 $IN[B] = \bigcap_{P \text{ is a predecessor of } B} OUT[P], B \text{ not initial}$  $OUT[B] = e\_gen[B] \bigcup (IN[B] - e\_kill[B])$  $IN[B1] = \phi$  $IN[B] = U, \text{ for all } B \neq B1 \text{ (initialization only)}$ 

- *B*1 is the intial or entry block and is special because nothing is available when the program begins execution
- IN[B1] is always  $\phi$
- U is the universal set of all expressions
- Initializing IN[B] to  $\phi$  for all  $B \neq B1$ , is restrictive

### Available Expression Computation - DF Equations (2)



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#### Available Expression Computation - An Example



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#### Available Expression Computation - An Example (2)



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# An Iterative Algorithm for Computing Available Expressions

for each block  $B \neq B1$  do { $OUT[B] = U - e_kill[B]$ ; } /\* You could also do IN[B] = U;\*/ /\* In such a case, you must also interchange the order of \*/ /\* IN[B] and OUT[B] equations below \*/ change = true; while change do { change = false; for each block  $B \neq B1$  do {

$$IN[B] = \bigcap_{\substack{P \text{ a predecessor of } B}} OUT[P];$$
  

$$oldout = OUT[B];$$
  

$$OUT[B] = e\_gen[B] \bigcup (IN[B] - e\_kill[B]);$$
  
if  $(OUT[B] \neq oldout)$  change = true;

## Live Variable Analysis

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- The variable *x* is *live* at the point *p*, if the value of *x* at *p* could be used along some path in the flow graph, starting at *p*; otherwise, *x* is *dead* at *p*
- Sets of variables constitute the domain of data-flow values
- Backward flow problem, with confluence operator  $\bigcup$
- *IN*[*B*] is the set of variables live at the beginning of *B*
- OUT[B] is the set of variables live just after B
- *DEF*[*B*] is the set of variables definitely assigned values in *B*, prior to any use of that variable in *B*
- *USE*[*B*] is the set of variables whose values may be used in *B* prior to any definition of the variable

$$DUT[B] = \bigcup_{\substack{S \text{ is a successor of } B}} IN[S]$$
$$IN[B] = USE[B] \bigcup (OUT[B] - DEF[B])$$
$$IN[B] = \phi, \text{ for all } B (\text{initialization only})$$











#### Live Variable Analysis: An Example - Final pass



# Data-flow Analysis: Theoretical Foundations

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# Foundations of Data-flow Analysis

- Basic questions to be answered
  - In which situations is the iterative DFA algorithm correct?
  - I How precise is the solution produced by it?
  - Will the algorithm converge?
  - What is the meaning of a "solution"?
- The above questions can be answered accurately by a DFA framework
- Further, reusable components of the DFA algorithm can be identified once a framework is defined
- A DFA framework  $(D, V, \land, F)$  consists of
  - D : A direction of the dataflow, either forward or backward
  - V : A domain of values
  - $\land$  : A meet operator; (*V*,  $\land$ ) form a semi-lattice
  - F : A family of transfer functions,  $V \longrightarrow V$

F includes constant transfer functions for the ENTRY/EXIT nodes as well

- A semi-lattice is a set V and a binary operator ∧, such that the following properties hold
  - V is closed under ∧
  - ② ∧ is idempotent  $(x \land x = x)$ , commutative  $(x \land y = y \land x)$ , and associative  $(x \land (y \land z) = (x \land y) \land z)$
  - **③** It has a *top* element,  $\top$ , such that  $\forall x \in V$ ,  $\top \land x = x$
  - It may have a *bottom* element,  $\bot$ , such that  $\forall x \in V, \bot \land x = \bot$
- The operator ∧ defines a partial order ≤ on V, such that x ≤ y iff x ∧ y = x

# Semi-Lattice of Reaching Definitions

- 3 definitions, {d1,d2,d3}
- V is the set of all subsets of {d1,d2,d3}
- $\land$  is  $\cup$
- The diagram (next slide) shows the partial order relation induced by ∧ (i.e., ∪)
- Partial order relation is  $\supseteq$
- An arrow,  $y \to x$  indicates  $x \supseteq y$  ( $x \le y$ )
- Each set in the diagram is a data-flow value
- Transitivity is implied in the diagram (a → b & b → c imples a → c)
- An ascending chain: (*x*<sub>1</sub> < *x*<sub>2</sub> < ... < *x*<sub>n</sub>)
- Height of a semi-lattice: largest number of '<' relations in any ascending chain
- Semi-lattices in our DF frameworks will be of finite height

#### Lattice Diagram of Reaching Definitions

 $y \rightarrow x$  indicates  $x \supseteq y$  ( $x \le y$ )



- $F: V \rightarrow V$  has the following properties
  - F has an identity function, I(x) = x, for all  $x \in V$
  - 2 *F* is closed under composition, *i.e.*, for  $f, g \in F$ ,  $f, g \in F$

Example: Again considering the R-D problem

- Assume that each quadruple is in a separate basic block
- $OUT[B] = GEN[B] \cup (IN[B] KILL[B])$
- In its general form, this becomes  $f(x) = G \cup (x K)$
- F consists of such functions f, one for each basic block
- Identity function exists here (when both G and K (GEN and KILL) are empty)

#### **Reaching Definitions Framework - Example**



Transfer functions:  $f_{d1}(x) = \{d1\} \cup (x - \{d4\})$   $f_{d2}(x) = \{d2\} \cup (x - \{d3\})$   $f_{d3}(x) = \{d3\} \cup (x - \{d2\})$   $f_{d4}(x) = \{d4\} \cup (x - \{d1\})$  $f_{d5}(x) = \{d5\} \cup (x - \Phi)$ 

Transfer functions for start and stop blocks are identity functions

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$$\begin{aligned} f_{B1} &= (f_{d2}.f_{d1})(x) \\ &= \{d2\} U (\{d1\} U (x - \{d4\}) - \{d3\}) \\ &= \{d1,d2\} U (x - \{d3,d4\}) \\ f_{B2} &= (f_{d4}.f_{d3})(x) \\ &= \{d3,d4\} U (x - \{d1,d2\}) \\ f_{B3} &= f_{d5} = \{d5\} U x \end{aligned}$$

#### Monotone and Distributive Frameworks

- A DF framework  $(D, F, V, \wedge)$  is monotone, if  $\forall x, y \in V, f \in F, x \leq y \Rightarrow f(x) \leq f(y)$ , OR  $f(x \wedge y) \leq f(x) \wedge f(y)$
- The reaching definitions framework is monotone
- A DF framework is distributive, if  $\forall x, y \in V, f \in F, f(x \land y) = f(x) \land f(y)$
- Distributivity  $\Rightarrow$  monotonicity, but not vice-versa
- The reaching definitions lattice is distributive

#### Iterative Algorithm for DFA (forward flow)

 $\{OUT[B1] = v_{init};$ for each block  $B \neq B1$  do  $OUT[B] = \top;$ while (*changes to any OUT occur*) do for each block  $B \neq B1$  do {

$$IN[B] = \bigwedge_{P \text{ a predecessor of } B} OUT[P];$$
  
 $OUT[B] = f_B(IN[B]);$ 

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### Reaching Definitions Framework - Example contd.



Needs 2 iterations to converge IN[B1] = IN[B2] =  $\Phi$ ; OUT[B1] = {d1,d2}; OUT[B2] = {d3,d4} IN[B3] = OUT[B1] U OUT[B2] = {d1,d2,d3,d4} OUT[B3] = {d5} U IN[B3] = {d1,d2,d3,d4,d5}

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